## TYPE THEORETICAL APPROACHES TO OPETOPES

Journées Logique Homotopie Catégories

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This presentation informally presents the main notions and results of [CHM18] (in preparation, draft available at chothanh.wordpress.com).

## Contents

Opetopes

The "named" approach

The "unnamed" approach

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Opetopes

## In a nutshell...

Opetopes are shapes (akin to globules, cubes, simplices, etc.) designed to represent the notion of composition in every dimension. As such, they were introduced in [BD98] to describe laws and coherence if weak higher categories.

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They are pasting diagrams where every cell is many-to-one. Here is an example of a 3-opetope:


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They are pasting diagrams where every cell is many-to-one. Here is an example of a 3-opetope:


Every cell above has dimension 2, so that a 3-opetope really is a pasting diagram of cells of dimension 2.

We further ask those cells of dimension 2 to be 2-opetopes, i.e. pasting diagram of cells of dimension 1 (the arrows).

We further ask those cells of dimension 1 to be 1-opetopes, i.e. pasting diagram (in a trivial way) of cells of dimension 0 (the points).

## Informal definition

## Definition

An $n$-opetope is a pasting diagram of $(n-1)$-opetopes

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An $n$-opetope is a pasting diagram of $(n-1)$-opetopes i.e. a finite set of $(n-1)$-opetopes glued along ( $n-2$ )-opetopes.

## Definition: low dimensions

- There is a unique 0-dimensional opetope, which we'll call the point


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## Definition: dimension 3

- 3-opetopes are pasting diagrams of 2-opetopes



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## Definition: dimension 4

- The induction goes on: 4-opetopes are pasting diagrams of 3-opetopes



## Definition: dimension 4

- The induction goes on: 4-opetopes are pasting diagrams of 3-opetopes


## This is getting out of hand...

## Motivation

## Problem

1. The graphical approach is neither formal nor manageable for dimensions $\geq 4$.

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## Problem

1. The graphical approach is neither formal nor manageable for dimensions $\geq 4$.
2. A formal definition either use $T$-operads [Lei04] or polynomial monads and trees [KJBM10], which are both unintuitive and difficult to manipulate.

## Solution

In this presentation, we give a rough sketch two ways to define opetopes syntactically.

The "named" approach

1. Take an opetope.

2. Take an opetope.

3. Give names to everything.

## Idea

1. Take an opetope.

2. Give names to everything.
3. Write down the graftings:

$$
A: \beta(i \leftarrow \alpha) \multimap h(c \leftarrow g(b \leftarrow f)) \multimap a \bullet \varnothing .
$$

4. ???
5. Profit!

## Syntax

- We start with a set of variable $\mathbb{V}=\amalg_{n \in \mathbb{N}} \mathbb{V}_{n}$, where elements of $\mathbb{V}_{n}$ represent $n$-cells.


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- The set of $n$-terms is defined as

$$
\begin{aligned}
\mathbb{T}_{n} & ::=\mathbb{V}_{n}\left(\mathbb{V}_{n-1} \leftarrow \mathbb{T}_{n}, \cdots\right) \\
& \mid \underline{\mathbb{V}_{n-1}}
\end{aligned}
$$

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\end{aligned}
$$

## Examples

For $a, b, c \in \mathbb{V}_{0}, f, g, h \in \mathbb{V}_{1}$,

$$
\begin{gathered}
a \in \mathbb{T}_{0}, \quad h(a \leftarrow g, b \leftarrow f) \in \mathbb{T}_{1}, \\
f(a \leftarrow f(a \leftarrow f), a \leftarrow f, a \leftarrow f) \in \mathbb{T}_{1}, \quad \underline{h} \in \mathbb{T}_{2} .
\end{gathered}
$$

## Syntax

- An $n$-type is a sequence of terms of the form

$$
s_{1} \multimap s_{2} \multimap \cdots \multimap s_{n} \multimap s_{n+1} \multimap \varnothing,
$$

where $s_{i} \in \mathbb{T}_{n+1-i}$.

## Syntax

- An n-type is a sequence of terms of the form

$$
s_{1} \multimap s_{2} \multimap \cdots \mapsto s_{n} \multimap s_{n+1} \multimap \varnothing \text {, }
$$

where $s_{i} \in \mathbb{T}_{n+1-i}$.

- A n-typing is an expression of the form

$$
t: T
$$

where $t \in \mathbb{T}_{n}$ and $T$ is an ( $n-1$ )-type.

## Main result of the named approach

Theorem
Derivable typings in system Opt! of the form

$$
\alpha: T
$$

where $\alpha \in \mathbb{V}_{n}$ (as opposed to just $\mathbb{T}_{n}$ ) are in bijective correspondence (up to renaming of variables) with n-opetopes.

## System Opt': the point rule

The first rule of Opt' states that we may create points without any prior assumption:
..point

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The first rule of Opt' states that we may create points without any prior assumption:

$$
\text { _ point } \quad \overline{x: \varnothing} \text { point }
$$

## System Opt': the degen-fill rule

This rule takes an opetope and produces a degenerate opetope from it: degen-fill

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degen-fill

$$
\frac{x: T}{\delta: \underline{x} \mapsto x \multimap T} \text { degen-fill }
$$

## System Opt': the fill rule

This rule takes a pasting diagram (that is, a term), and creates an opetope by "filling" it:


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This rules glues an opetope to a pasting diagram of the same dimension:


## System Opt＇：the graft rule

This rules glues an opetope to a pasting diagram of the same dimension：

$$
\begin{aligned}
& \text { 变, 们 } \\
& \vec{V} \vec{V} \text { graft-a } \\
& \frac{t: s \multimap T \quad x: y \multimap U}{t(a \leftarrow x): s[y / a] \mapsto T} \text { graft }-a
\end{aligned}
$$

## Example 1

Let's derive


## Example 1

## Let's derive



Derivation of $\alpha$

## Example 1

Let's derive


Derivation of $\beta$

## Example 1

Let's derive


And we assemble to get $A$

$$
\begin{gathered}
\frac{\beta: h(c \leftarrow i) \multimap a \multimap \varnothing \quad \alpha: g(b \leftarrow f) \multimap a \bullet \varnothing}{\beta(i \leftarrow \alpha): \underbrace{h(c \leftarrow i)[g(b \leftarrow f) / i]}_{\equiv h(c \leftarrow g(b \leftarrow f))} \mapsto a \multimap \varnothing} \text { graft-i } \\
\frac{A: \beta(i \leftarrow \alpha) \multimap h(c \leftarrow g(b \leftarrow f)) \multimap a \multimap \varnothing}{} \text { fill }
\end{gathered}
$$

## Example 2

Let's derive


## Example 2

Let's derive


Top left part

$$
\frac{\overline{a: \varnothing} \text { point }}{\alpha: \underline{a} \bullet a \bullet \varnothing} \text { degen-fill }
$$

## Example 2

Let's derive


## Bottom part

## Example 2

Let's derive


And we assemble

$$
\begin{align*}
& \frac{\beta: g(b \leftarrow f) \multimap a \multimap \varnothing \quad \alpha: \underline{a} \mapsto a \bullet \varnothing}{a=b \vdash \beta(f \leftarrow \alpha): \underbrace{g(b \leftarrow f)[a / f]}_{\equiv g} \multimap a \bullet \varnothing} \text { graft }-f \\
& a=b \vdash A: \beta(f \leftarrow \alpha) \multimap g \multimap a \bullet \varnothing \tag{fill}
\end{align*} \text { fill }
$$

The "unnamed" approach

## Idea

Since opetopes are pasting diagrams whose cells are many-to-one, they can be represented as trees:


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Since opetopes are pasting diagrams whose cells are many-to-one, they can be represented as trees:


Then a cell in a pasting diagram no longer needs to have a name, it can be identified by its address in that tree.

## Idea: dimension 0 and 1

Denote by the unique 0-opetope, a.k.a. the point:

## Idea: dimension 0 and 1

Denote by the unique 0-opetope, a.k.a. the point: and by the unique 1-opetope, a.k.a. the arrow:

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We can represent as a node of a tree as follows:


## Idea: dimension 0 and 1

Denote by the unique 0-opetope, a.k.a. the point:
and by. the unique 1-opetope, a.k.a. the arrow:

We can represent as a node of a tree as follows:


Let us add address information.

## Idea: dimension 2

Then we can:

1. create a tree with that node representing -

| - |
| :---: |
|  |  |
|  |  |
|  |  |
|  |  |
|  |  |
|  |  |

## Idea: dimension 2

Then we can:

1. create a tree with that node representing -


2. consider that tree like a node, where the input edges are the nodes of said tree

## Idea: dimension 2

Then we can:

1. create a tree with that node representing -

2. consider that tree like a node, where the input edges are the nodes of said tree
3. be convinced that this is a good representation of some 2-opetope!

## Idea: dimension 2

Depending on the original tree, we obtain different 2-opetopes:


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Depending on the original tree, we obtain different 2-opetopes:


## Idea: dimension 2

Depending on the original tree, we obtain different 2-opetopes:


## Idea: dimension 3

From there, repeat the process!

$\leadsto$


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## Syntax

We now want a syntactical description of such trees.

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Solution

$\leadsto$


In an n-opetope, every node is decorated by ( $n-1$ )-opetope,

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Solution

$\leadsto$


In an $n$-opetope, every node is decorated by ( $n-1$ )-opetope, but ( $n-1$ )-opetope does not uniquely identify a node.

## Syntax

We now want a syntactical description of such trees.
Solution


In an n-opetope, every node is decorated by ( $n-1$ )-opetope, but ( $n-1$ )-opetope does not uniquely identify a node. But addresses do! So we just need to describe a partial map

$$
\mathbb{A} \longrightarrow \mathbb{O}_{n-1}
$$

## Syntax

We encode opetopes recursively as follows:


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Reminder

$$
\left.\underline{2}=* \left\lvert\, \begin{array}{|l}
* \\
{[*]} \\
*
\end{array}\right.\right]
$$

## Syntax

We encode opetopes recursively as follows:


Reminder

$$
\underline{2}=\quad \begin{aligned}
& * \\
& * \\
& *
\end{aligned} \quad[\epsilon] \quad[\epsilon] \leftarrow \square
$$

## Syntax

We encode opetopes recursively as follows:


$$
\leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow:} \\
{[*] \leftarrow!}
\end{array}\right.} \\
{[[\epsilon]] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow:} \\
{[*] \leftarrow}
\end{array}\right.}
\end{array}\right.
$$

Reminder

$$
\underline{2}=: \begin{gathered}
* \\
: \\
:[*] \\
:[\epsilon]
\end{gathered}=\left\{\begin{array}{l}
{[\epsilon] \leftarrow} \\
{[*] \leftarrow}
\end{array}\right.
$$

## Syntax

We encode opetopes recursively as follows:


Convention

$$
\text { - }=\{* \leftarrow
$$

## Syntax

We encode opetopes recursively as follows:


$$
m s\left\{\begin{array}{l}
{[\epsilon] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{* \leftarrow} \\
{[*] \leftarrow\{* \leftarrow}
\end{array}\right.} \\
{[[\epsilon]] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{* \leftarrow} \\
{[*] \leftarrow\{* \leftarrow}
\end{array}\right.}
\end{array}\right.
$$

Convention

$$
\cdot=\{* \leftarrow 1
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& : \\
& \underline{1} \cdot\left[\begin{array}{lc}
{[\epsilon]}
\end{array}\right]
\end{aligned}
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]]
\end{aligned}
$$

$$
\begin{aligned}
& \leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{1}} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
\end{aligned}
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& \cdot \\
& \underline{1} \cdot[\epsilon]
\end{aligned} \quad m \rightarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{1}} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
$$

Reminder

$$
\underline{1}=:\left.\right|^{*}[\epsilon]=\{[\epsilon] \leftarrow
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[\epsilon]] \\
& \text { - } 1 \cdot[\epsilon] \quad \leadsto \Rightarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon]} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
\end{aligned}
$$

Reminder

$$
\underline{1}=\left.\right|^{*}[\epsilon]=\{[\epsilon] \leftarrow ■
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& - \\
& \underline{1}
\end{aligned}\left[[ \epsilon ] \quad \left[\begin{array} { l } 
{ [ \epsilon ] }
\end{array} \leadsto \left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon] \leftarrow} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.\right.\right.
$$

Reminder

$$
=\{* \leftarrow 1
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& :\left[\begin{array}{l}
{[\epsilon]} \\
1
\end{array}:[\epsilon]\right. \\
& \cdot
\end{aligned} \quad \sim \rightarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{* \leftarrow} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
$$

Reminder

$$
\square=\{x \leftarrow
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& :\left[\begin{array}{l}
{[\epsilon]} \\
1 \\
\bullet
\end{array}:[\epsilon]\right.
\end{aligned} \quad \leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{* \leftarrow} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
$$

Reminder + convention

$$
\underline{0}=* \quad\{\|
$$

## Syntax: examples

$$
\begin{aligned}
& \underline{0} \cdot[[\epsilon]] \\
& :[\varepsilon] \\
& 1 \\
& -
\end{aligned} d[\epsilon] \quad \leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{* \leftarrow *} \\
{[[\epsilon]] \leftarrow\{\{ }
\end{array}\right.
$$

Reminder + convention

$$
\underline{0}=* \quad\{\|
$$

Syntax: examples


## Syntax: examples

2

$$
\leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{2}} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
$$

## Syntax: examples

Reminder

$$
\underline{2}=\bullet_{\bullet}^{*} \cdot \stackrel{*}{*} \begin{aligned}
& * \\
& \bullet[\epsilon]
\end{aligned}=\left\{\begin{array}{l}
{[\epsilon] \leftarrow} \\
{[*] \leftarrow}
\end{array}\right.
$$

## Syntax: examples

Reminder

## Syntax: examples

Reminder

$$
=\{* \leftarrow 1
$$

## Syntax: examples

$$
\begin{aligned}
& \text { = } \\
& \leadsto\left\{\begin{array}{l}
{[\epsilon] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{* \leftarrow} \\
{[*] \leftarrow\{* \leftarrow} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array},\right.}
\end{array}\right.
\end{aligned}
$$

Reminder

$$
\cdot=\{* \leftarrow 1
$$

## Syntax: examples

$$
\text { : } \quad \frac{0}{[[*]]} \sim\left\{\begin{array}{l}
{[\epsilon] \leftarrow\left\{\begin{array}{l}
{[\epsilon] \leftarrow\{* \leftarrow} \\
{[*] \leftarrow\{* \leftarrow}
\end{array}\right.} \\
{[[\epsilon]] \leftarrow \underline{0}}
\end{array}\right.
$$

Reminder

$$
\underline{0}=* \quad\{\quad\{
$$

## Syntax: examples



Reminder

$$
\underline{0}=\bullet \mid=\left\{\int\right.
$$

## Syntax: examples



## Syntax: examples



## Syntax: examples



Reminder

$$
\begin{aligned}
& \cdot \bullet[\epsilon]
\end{aligned}
$$

## Syntax: examples



Reminder

$$
\underline{3}=\quad \bullet \cdot \left\lvert\, \begin{aligned}
& * \\
& \bullet \\
& \bullet * * *] \\
& *
\end{aligned}=\left\{\begin{array}{l}
{[\epsilon] \leftarrow \bullet} \\
{[*] \leftarrow!} \\
{[* *] \leftarrow!}
\end{array}\right.\right.
$$

## Syntax: examples



Reminder

$$
1=:\left.\right|^{*}[\epsilon]=\{[\epsilon] \leftarrow
$$

## Syntax: examples



Reminder

$$
1=:\left.\right|^{*}[\epsilon]=\{[\epsilon] \leftarrow
$$

## Syntax: examples



Reminder

## Syntax: examples



Reminder

$$
\underline{2}=\quad \begin{aligned}
& * \\
& * \\
& * \\
& *
\end{aligned} \quad[\epsilon] \quad[\epsilon] \leftarrow ■
$$

## Syntax: examples



Reminder

$$
=\{* \leftarrow 1
$$

## Syntax: examples



Reminder

$$
\text { - }=\{* \leftarrow 1
$$

## Syntax

## Question

Is this an opetope?

$$
\begin{aligned}
& \left\{[ \epsilon ] \leftarrow \left\{\begin{array}{l}
{[*] \leftarrow,} \\
{[* *] \leftarrow} \\
{[* * *] \leftarrow}
\end{array}\right.\right. \\
& {[* *] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow\{[\epsilon] \leftarrow *} \\
& {\left[[ * * * ] \leftarrow \left\{\begin{array}{l}
{[\epsilon] \leftarrow\{[\epsilon] \leftarrow *} \\
{[*] \leftarrow} \\
{[* *] \leftarrow}
\end{array}\right.\right.} \\
& {[[\epsilon]] \leftarrow\{[\epsilon] \leftarrow\{* \leftarrow *} \\
& {[[[\epsilon]]] \leftarrow\left\{\begin{array}{l}
{[[[*]]] \leftarrow\{* \leftarrow *} \\
{[*] \leftarrow\{* \leftarrow}
\end{array}\right.} \\
& {[[\text { ***]] } \leftarrow}
\end{aligned}
$$

## System Opt?

The set of preopetopes $\mathbb{P}$ is defined by the following grammar:

$$
\begin{aligned}
\mathbb{P}: & := \\
& \mid \\
& \left\{\begin{array}{l}
\mathbb{A} \leftarrow \mathbb{P} \\
\vdots \\
\mathbb{A} \leftarrow \mathbb{P}
\end{array}\right. \\
& \mid\{\mathbb{P}
\end{aligned}
$$

## System Opt?

The set of preopetopes $\mathbb{P}$ is defined by the following grammar:

$$
\begin{aligned}
& \mathbb{P}::= \\
& \text { | }\left\{\begin{array}{l}
\mathbb{A} \leftarrow \mathbb{P} \\
\vdots \\
\mathbb{A} \leftarrow \mathbb{P}
\end{array}\right. \\
& \text { \| }\left\{\int \mathbb{P}\right.
\end{aligned}
$$

The Opt? system aims to characterize preopetopes that actually are opetopes:

## Theorem

Derivable preopetopes in system Opt? are in bijective correspondence with opetopes.

## System Opt? ${ }^{\text {? }}$ the point rule

The first rule of Opt? states that we may create points without any prior assumption:
_. point

## System Opt? ${ }^{\text {? }}$ the point rule

The first rule of Opt? states that we may create points without any prior assumption:
. point

- point


## System Opt? ${ }^{\text {? }}$ the degen rule

This rule takes an opetope and produces a degenerate opetope from it:


## System Opt? ${ }^{\text {? }}$ the degen rule

This rule takes an opetope and produces a degenerate opetope from it:

$\frac{p}{\left\{\int p\right.}$ degen

## System Opt?: the shift rule

This rule takes an opetope p and produces a new opetope having a unique node, decorated in p :


## System Opt?: the shift rule

This rule takes an opetope p and produces a new opetope having a unique node, decorated in p :


## System Opt? ${ }^{\text {? }}$ the graft rule

This rule glues an $n$-opetope $q$ to an $(n+1)$-opetope $p$, the latter really just being a pasting diagram of $n$-opetopes:

graft-[b]

## System Opt?: the graft rule

This rule glues an $n$-opetope $q$ to an $(n+1)$-opetope $p$, the latter really just being a pasting diagram of $n$-opetopes:

(we omitted some technical assumptions that ensure this operation is geometrically meaningful)

## Example

The proof tree of
is:

- point


## Example

The proof tree of

is:

$$
\frac{\square \text { point }}{\{[\epsilon] \leftarrow} \text { shift }
$$

## Example

The proof tree of

is:

$$
\frac{\square \text { point }}{\{* \leftarrow} \text { shift }
$$

## Example

The proof tree of

is:

$$
\begin{gathered}
\frac{\square \text { point }}{\{* \leftarrow} \text { shift } \\
\{[\epsilon] \leftarrow\{* \leftarrow \\
\text { shift }
\end{gathered}
$$

## Example

The proof tree of

is:

## Example

The proof tree of

is:

## Example

The proof tree of

is:

## Example

The proof tree of

is:

$$
\begin{aligned}
& \frac{\square \text { point }}{\{* \leftarrow} \text { shift } \\
& \text { shift } \frac{\downarrow}{\{[\epsilon] \leftarrow} \text { shift } \\
& \begin{cases}{[\epsilon] \leftarrow\{* \leftarrow} & \text { graft }-[*] \\
{[*] \leftarrow\{* \leftarrow} & \{[\epsilon] \leftarrow\end{cases} \\
& \left\{\begin{array}{l}
{[\epsilon] \leftarrow\{* \leftarrow} \\
{[*] \leftarrow\{* \leftarrow} \\
{[* *] \leftarrow\{* \leftarrow}
\end{array}\right.
\end{aligned}
$$

## Examples

Write

## Examples

The proof tree of

is:
$\vdots$
$\underline{2}$

## Examples

The proof tree of

is:

$$
\frac{\underline{2}}{\{[\epsilon] \leftarrow \underline{2}} \text { shift }
$$

## Examples

The proof tree of

is:

$$
\frac{\frac{\underline{2}}{\{[\epsilon] \leftarrow \underline{2}} \text { shift }}{} \begin{array}{ll}
\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{2}} \\
{[[*]] \leftarrow \underline{2}}
\end{array}\right. & \text { graft }-[[*]]
\end{array}
$$

## Example

The proof tree of

is
$\vdots$
1

## Example

The proof tree of

is

## Example

The proof tree of

is

$$
\frac{\frac{\underline{\vdots}}{\{[\epsilon] \leftarrow \underline{1}} \text { shift }}{\frac{\vdots}{\underline{0}}} \begin{array}{ll}
\{[\epsilon] \leftarrow 1 & \\
\{[\epsilon]] \leftarrow \underline{0}
\end{array} \quad \text { graft }-[[\epsilon]]
$$

## Example

The proof tree of

is
$\vdots$
$\underline{2}$

## Example

The proof tree of

is

$$
\frac{\underline{2}}{\{[\epsilon] \leftarrow \underline{2}} \text { shift }
$$

## Example

The proof tree of

is

$$
\frac{\frac{\underline{2}}{\{[\epsilon] \leftarrow \underline{2}} \text { shift } \quad \begin{array}{l}
\underline{0} \\
\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{2}} \\
{[[*]] \leftarrow \underline{0}}
\end{array}\right. \\
\text { graft }-[[*]]
\end{array}}{}
$$

## Example



## Example



## Example



## Example



$$
\begin{array}{ll}
\frac{\underline{3}}{\{[\epsilon] \leftarrow \underline{3}} \text { shift } & \begin{array}{l}
\vdots \\
\underline{2} \\
\text { graft }-[[*]]
\end{array} \\
\begin{cases}{[\epsilon] \leftarrow \underline{3}} \\
{[[* *] \leftarrow \underline{2}}\end{cases} & \begin{array}{l}
\underline{1}
\end{array} \\
\left\{\begin{array}{l}
{[\epsilon] \leftarrow \underline{3}} \\
{[[*]] \leftarrow} \\
{[[* *]] \leftarrow 1}
\end{array}\right.
\end{array}
$$

Conclusion

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1. in a "named" way, using terms and system Opt';
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- In [CHM18] (see link on the first slide for a draft), we also present variants of those systems for opetopic sets.
- We are experimenting with those new tools to automatically check coherence laws for an appropriate definition of opetopic $\omega$-groupoid.


## Thank you for your attention!

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